# Table of Contents

**Introduction**

**Benefits of Informix Extended Parallel Server 8.3**

**Informix Extended Parallel Server 8.3 Architectural Overview**

- Request Manager  
- Query Optimizer  
- Metadata Manager  
- Scheduler  
- A True Shared-Nothing Database Architecture

**Optimized for Data Warehouse/Decision Support Processing**

- Simplify Data Access and Analysis Through Star Schema  
- Very Large Data Storage Capacity  
- Fast Data Access Through Efficient Indexing Methods  
- Enhanced Join Methods  
- Enhanced SQL Extensions

**Database Administration and Management**

- Query Management  
- Parallel Loader  
- Alter Fragment

**Conclusion**
Data warehousing has become a critical component in management’s quest to turn transactional data into decision-making information. Unlike traditional on-line transaction processing (OLTP) systems that automate day-to-day operations, a data warehouse provides an environment in which an organization can evaluate and analyze enterprise data over time. It allows a business to reconstruct history and accurately compare data from different time periods, providing the information necessary for strategic planning and decision making.

Because data warehouse operations are typically complex, analytical, and involve a large amount of data, businesses are increasingly deploying shared-nothing hardware architectures such as massively parallel (MPP) systems and clusters of symmetrical processing (SMP) systems to ensure performance and scalability. These systems are made up of independent uniprocessors or SMP (referred to as nodes) that are connected through a high-speed, point-to-point, interconnected network. Shared-nothing hardware architectures are ideal for running data-intensive operations because nodes are not bounded by a common system bus or operating software. They are well-suited for data warehouse environments—characterized by exponential growth in database size and processing—because they are easily expandable and configurable.

Database management systems are equally important in the development and deployment of data warehouses. Applications that access data warehouses—also known as decision-support (DSS) applications—typically involve scans of entire tables, manipulation of data, multiple joins, and creation of temporary tables. These operations are pushing the limits of traditional database management systems in the areas of performance, scalability, and availability. Additionally, many database management systems simply cannot take full advantage of shared-nothing hardware architectures.

Informix® Extended Parallel Server™ 8.3 addresses the complex needs of data warehouses and DSS applications. Designed specifically to handle the demands of very large databases (VLDBs), Informix Extended Parallel Server 8.3 offers a shared-nothing database engine, complementing the shared-nothing hardware systems. This highly optimized data engine utilizes all available hardware resources including CPU, memory, disks, and more, delivering mainframe-caliber scalability, manageability, and availability, while requiring minimal operating system overhead.

In addition to a shared-nothing database engine, Informix Extended Parallel Server 8.3 offers a complete set of features to further enhance the performance of decision support queries. These features include enhanced SQL extensions and join methods to improve the execution of large decision-support queries, new indexing methods to accelerate access to data, and a graphical administration environment to ease management of large volumes of data.
Benefits of Informix Extended Parallel Server 8.3

True Linear Scalability
Informix Extended Parallel Server 8.3 is designed to meet the needs of users as their requirements grow, in data warehouse size, numbers of users, volume of transactions, and complexity of analyses. Its unique “shared nothing” design ensures true linear scalability, allowing businesses to make the most efficient use of available hardware resources to deliver the highest level of performance for all types of data warehouse operations.

Fastest Ad-Hoc Query Performance
Understanding that management needs timely information to make key decisions about their businesses, Informix Extended Parallel Server 8.3 is specifically designed to provide an optimized environment maximized for all types of decision-support operations. Informix Extended Parallel Server 8.3 offers a host of features to speed the execution of complex, analytical queries, with performance up to 100 times faster than on the same hardware. Resource-management utilities ensure optimum distribution of system resources—including CPU, memory, and disks—and increase processing efficiency to further enhance query performance. The result is query response time measured in minutes rather than hours, and hours rather than days, ensuring that decision-makers get fast access to the accurate information they need to keep their businesses competitive.

High Availability and “On the Fly” Reconfiguration
A highly available database environment is important, given that DSS queries are becoming more complex and analytical, and data volumes involved in the queries are increasing at an exponential rate. Informix Extended Parallel Server 8.3 has the ability to be rapidly reconfigured so that if a processor fails, another one can be switched to take over its workload.

Informix Extended Parallel Server 8.3 also allows processors to be added at times of peak load, simply by restarting the database. There is no time-consuming re-initialization required. This maximizes hardware utilization by eliminating the need for permanently configured systems (sometimes referred to as hot replacement) that are idle most of the time.

Flexibility for Meeting Dynamic Needs
A flexible database environment is important in supporting the dynamic needs of a data warehouse. To efficiently provide timely information for strategic planning, applications must be designed around business needs, rather than being limited by technology and database design. Administrators typically cannot predict the type, quantity, and complexity of queries being submitted, so the database must provide the flexibility to support the changing processing requirements.
Because different DSS operations have distinct processing requirements for achieving optimum performance, Informix Extended Parallel Server 8.3 offers multiple implementation options on such key features as schema design, data fragmentation, skew management, indexing, table joins, and resource management. These options offer the flexibility to choose the best execution path to obtain the fastest response time and allow Informix Extended Parallel Server 8.3 to efficiently handle different processing loads without performance degradation.

**Hardware Independence**

Informix Extended Parallel Server 8.3 is available on a wide variety of UNIX® systems and processing architectures. It takes full advantage of SMP, uniprocessor, NUMA, cluster and MPP systems, both 32 and 64 bit. Informix Extended Parallel Server 8.3 maximizes the return on users’ hardware investment by capitalizing on the strengths of these different architectures.
Informix Extended Parallel Server 8.3 is the only technology designed from the ground up to address the complexities of very large volume, ad-hoc decision support query processing for many users.

Like the hardware that it supports, Informix Extended Parallel Server 8.3 takes a shared-nothing approach to managing data, thereby greatly minimizing operating system overhead and reducing network I/O. To achieve this level of independence, each node runs its own instance of Informix Extended Parallel Server 8.3 that consists of basic services for managing its own logging, recovery, locking, and buffer management. This instance of the database is called a co-server.

Each co-server “owns” a set of disks and the partitions of the database that reside on these disks. A co-server typically has physical accessibility to other disks owned by other co-servers for failover purposes, but in normal operation, each co-server only accesses disks that it owns. (See Figure 1.)

To optimize performance, the system catalog containing information about the way in which the data is distributed can be cached across the nodes. Additionally, smaller, frequently accessed tables can be replicated across the nodes to further enhance performance.

Although multiple instances of the Informix Extended Parallel Server 8.3 are running, all of the co-servers cooperate to provide the image of a single, large server. This single-system image is provided to both general database users and also to system and database administrators.

Different clients can connect to different co-servers. The co-server that the client connects to is called the connection co-server. The connection co-server determines if a client request can be satisfied with data that resides on the co-server alone, or whether it requires data that resides on other co-servers. If the co-server requires data that resides on another co-server, it interacts and coordinate activities with participating co-servers. For example, client A connects to co-server 1. After determining that it does not have the necessary data to complete the request, co-server 1, the connection co-server, calls co-server 2, which becomes the participating co-server to co-server 1, to complete the request.
Informix Extended Parallel Server 8.3 can achieve this level of coordination by making intelligent decisions about how to divide the query and where to send the SQL operations to be performed on different nodes. (See Figure 2.) The server services responsible for making such decisions include the request manager, query optimizer, metadata manager, and the scheduler. These services are tightly integrated into the core kernel of Informix Extended Parallel Server 8.3.

![Figure 2](image)

Database services make intelligent decisions about how queries should be executed.

**Request Manager**

Resident on every co-server is a request manager (RQM), which makes decisions about how a query should be divided and distributed while ensuring that the workload is balanced across the nodes. To determine whether a user request should involve multiple co-servers, RQM works with other services: the query optimizer to determine the best way of executing a request; the metadata manager to determine where the data resides; and the scheduler to distribute the request.

The RQM on the co-server where the user connects is called the primary RQM for the user session. If a request involves execution on multiple co-servers, the primary RQM passes along sufficient context information so that the RQM on the other co-servers can establish local session context for those users.

**Query Optimizer**

The query optimizer is responsible for determining the best way to perform a specific query. It is cost-based, meaning the optimizer generates multiple query plans, computes a cost for each plan, then chooses the lowest-cost plan. A query plan is simply a distinct method of executing a query that takes into account the order in which tables are read, how they are read (by index or sequentially), and how they are joined with other tables in the query. Using pertinent information provided by the metadata manager, the query optimizer determines the degree of parallelism of the request, and sends the execution plan to the scheduler for distribution.
**Metadata Manager**

Metadata is information about how data is distributed across the nodes. It typically resides on one node but can be mirrored to provide fault tolerance. Metadata is managed by a metadata manager (MDM), which also resides on each node. The MDMs on all co-servers cooperate to provide accessibility to the metadata of all the databases stored in a given system, regardless of where that metadata is stored. Updates of such metadata are also handled transparently by the system, although the updates are actually coordinated by the MDM that resides on the co-server where a given database’s metadata is stored.

**Scheduler**

The scheduler also resides on every co-server. Its responsibility is to distribute execution tasks within the system. The scheduler is responsible for activating the plan at co-server locations where proper resources are locally available. Dependent upon the execution plan provided by the query optimizer, the type of task being executed, and the priority setting of the user request, the scheduler determines whether a given request should be accomplished in a serial or parallel fashion.

**A True Shared-Nothing Database Architecture**

Critical to a shared-nothing hardware architecture is a complementary shared-nothing software architecture. Informix Extended Parallel Server 8.3 can deliver a true shared-nothing architecture through partitioning of data, partitioning of control, and partitioning of execution. The optimization of these three areas enables Informix Extended Parallel Server 8.3 to significantly minimize operating system overhead and network I/O, thereby delivering excellent linear scalability and speedups across very large systems.

**Partition of Data**

On a single system, Informix database servers support local table partitioning, which enables physical division of large tables and indexes into smaller sections so that they can be distributed across multiple disks. Local table partitioning is extremely effective in improving parallel processing, ensuring high availability, and enabling database administration from a single system.

Informix Extended Parallel Server 8.3 provides advance data partitioning algorithms to enable intelligent distribution of tables and indexes across multiple nodes. This optimization provides the basis for parallel execution of SQL operations among nodes, allowing Informix Extended Parallel Server 8.3 to distribute and execute operations associated with large complex decision support queries across multiple nodes and disks in parallel.

After a table has been partitioned, each data partition is read and written only by the co-server that owns it. Although disks are accessible by other co-servers in the event of a node failure, in normal operation a disk is only read by the co-server to which it is attached. This approach ensures that I/O operations are balanced across all nodes and
disks within the cluster, thus minimizing expensive network I/O operations and eliminating I/O bottlenecks. Data partitioning also improves very large database manageability and availability by enabling all maintenance operations—such as load, index, builds, backup, and recovery—to take place in parallel across all nodes.

Tables and indexes can be partitioned using a variety of methods, including simple round-robin (every record goes to the next partition in the sequence); hashed (an algorithm applied to the record key determines its partition number); range (data is divided based on key ranges); and expression (each partition gets a set of records based on their key value). To ensure performance and manageability, partitions can be monitored and tuned as needed.

With the Informix Extended Parallel Server 8.3, Informix offers a new data partition method called hybrid partitioning. Hybrid partitioning supports both tables and locally detached indexes to produce table or index partitioning that is well distributed, yet logically partitioned. It is a flexible, two-level partitioning scheme, combining expression and hash partitioning. By using hybrid partitioning, a table can be partitioned based on expression, such as date or time, and then partitioned by hash on other columns in the table. This ensures that data is well distributed via the internal hash function, yet easy to manage and use through expression ranges.

Hybrid partitioning is particularly useful for minimizing non-uniform distribution of data that is often referred to as skew. Skew should be avoided as much as possible because it can result in inefficient utilization of system resources. For example, if an order table is range-partitioned using the first letter of a customer’s last name, and each letter of the alphabet has its own disk, the disks for letters S and T have the greatest number of orders, while the disks for letters V and Z have the fewest number of orders. Therefore, if an operation such as an aggregation was performed on these disks, disks containing S and T will be very active while disks containing V and Z will be relatively inactive (See Figure 3).
Skew can be avoided in the previous example by hash partitioning the orders on a unique key so that all nodes contain customers with the last names of all letters in the alphabet. Then, among the disks within each node, range partitioning can be used based on the first letter of a customer’s last name. (See Figure 4.)

By using hybrid partitioning, customers can ensure that system resources are efficiently utilized by keeping workload balanced among disks and I/Os optimized within each disk.

**Partition of Control**

Informix Extended Parallel Server 8.3 provides each co-server with basic database services for managing its own locking, buffer management, transaction logging, and recovery for the database objects that it owns, thus providing each co-server with the independence to manage its own data. This partitioning of the database services across all the co-servers is referred to as partitioning of control. (See Figure 5.)

While each co-server manages and maintains its own data, it is aware of where other data resides through the metadata manager located on every node. If a co-server requires a piece of data that it does not own, the co-server sends an execution request to the co-server that owns the data to retrieve the data, process the data based on the execution request, and return the results to the originating co-server. The process of sending an execution request to another co-server is called function shipping.
For example, node 1 receives a user request to perform a two-table join. Node 1 metadata manager indicates that the first table resides on node 2 and the second table resides on node 3. Because both tables are fairly small, the query plan devised by the query optimizer calls for a sort-merge join, whereby both tables are scanned, sorted on the join key, and merged based on the join criteria. The scheduler distributes (function ships) the execution tasks to both node 2 and node 3 to perform the necessary scanning and sorting of table 1 and 2, respectively. The results of the scans and the sorts are returned to node 1 for execution of the merge operation.

Function-shipping enlists the processing cycles of other nodes, hence significantly reducing the amount of time in the execution of a query. (See Figure 6.)

**Partitioning of Execution**

Partitioning of execution refers to the breaking down of a query into subtasks and executing them on multiple nodes in parallel. Partitioning of execution is extremely useful in decision-support queries where large volumes of data are being scanned, joined, and sorted across multiple co-servers.

To break down a query and efficiently execute the resulting subtasks across all available CPUs and nodes, subtasks must be able to communicate and cooperate with one another. For example, a two-table join operation can be broken down into four subtasks: scan, join, sort, and write. These operations can be performed concurrently on multiple nodes. That is, as soon as the scan subtask has scanned enough information from the disk, the results can be transmitted to a join subtask before the scan has been completed. As soon as the join subtask has joined enough data, the results can be transmitted to a sort subtask before the join has been completed, and so on.

The scan subtask can be broken into multiple scan subtasks so that they can execute independently and in parallel across multiple nodes. For example, if a table is partitioned using range partitioning, node 1 can be responsible for scanning customer records with last names starting with letters A through D. Node 2 can be responsible for records starting with letters E through H, node 3 for records starting with letters I through L, and so forth. As soon as enough data has been scanned by these scan subtasks,
results are immediately transmitted to join
subtasks for execution on multiple nodes. When enough data has been joined by the
join subtasks, results are immediately
transmitted to sort subtasks for execution
on multiple nodes, and so on.

One method for achieving communication
and cooperation among subtasks in a cluster
environment is to employ intraserver and
interserver parallelism. Intraserver parallelism
enables “pipelining”—or transmission of
data—across a series of subtasks running
on multiple CPUs within a node, and inter-
server parallelism enables pipelining of
data across a series of subtasks running on
different nodes. This coupling of intraserver
and interserver communication can increase
performance exponentially.

Informix Extended Parallel Server 8.3 offers
an efficient pipeline dataflow model to ensure
optimal intraserver and interserver communi-
cation. Intraserver communication among
subtasks located on the same SMP node is
achieved via shared memory while interserver
communication among subtasks on different
nodes is achieved using networked messages
across a high speed interconnect. Informix
Extended Parallel Server 8.3 is unique in
providing these two levels of partitioned
execution, which ensure performance and
scalability for MPP environments with a
larger number of uniprocessor nodes and
cluster environments with a smaller number
of SMP nodes. (See Figure 7.)

Data Failover
A shared-nothing database architecture is
critical to ensuring a highly available data-
based environment. Any failure within a node
or database server is localized, affecting only
the data and processing of the data on that
particular node. The remaining portion of the
database residing on other nodes is continu-
ously available and accessible. Similarly, the
remaining database servers in the clustered
system can continue processing.

As discussed earlier, each co-server owns a
set of disks and the partitions of the database
that reside on these disks. These disks are
typically dual-ported to other co-servers to
guard against unexpected failures. If a hard-
ware or software problem brings down a
c0-server on a node, an alternate co-server
takes over the disks of the failed co-server to
ensure that the data is available and accessible.

Figure 7
Informix Extended Parallel
Server 8.3 offers two levels of
parallel execution to optimize
performance within nodes
and across nodes.
For example, suppose Informix Extended Parallel Server 8.3 is running on three separate nodes. Co-server 1 owns disks 1 and 2, co-server 2 owns disks 3 and 4, and co-server 3 owns disks 5 and 6. To ensure continuous availability in the event of a failure, disks 1 and 2 are dual-ported to co-server 2, disks 3 and 4 are dual-ported to co-server 3, and disks 5 and 6 are dual-ported to co-server 1. The dotted lines in Figure 8 represent the way disks are dual ported.

In the event of a failure, the alternate co-server takes over ownership of the data disks and logs belonging to the failed node. This process is also known as data failover. After the alternate co-server has taken over the disks on the failed node, fast recovery is performed to restore the affected portion of the database to a physical and logical consistency. When recovery is complete, all operations are dynamically redistributed to the alternate nodes.

Using the example below, should node 2 or co-server 2 fail unexpectedly, co-server 3 takes over disks 3 and 4 to ensure continuous data availability on these disks (see Figure 9.)

![Figure 8](image1.png)

Dual-ported disks ensure high availability.

![Figure 9](image2.png)

Informix Extended Parallel Server 8.3 data failover.
The shared-nothing database architecture provides a solid foundation for maximizing performance, scalability, and availability. To further refine its efficiency for data warehousing environments, Informix Extended Parallel Server 8.3 incorporates a host of high-end features and enhancements designed specifically for decision support processing. These features and enhancements include:

- a new database design to simplify access and analysis of data;
- support for very large databases;
- new indexing methods to speed up access to data;
- enhanced join methods to optimize performance of join operations; and
- SQL extensions to increase the speed of execution for large, decision support queries.

Simplify Data Access and Analysis Through Star Schema

To ensure easy access to vast amounts of data, Informix Extended Parallel Server 8.3 supports a dimensional database design known as star schema. (See Figure 10.) Star schema simplifies access and analysis of information, allowing complex and analytical queries to be processed in a fraction of the time it would take with a traditional relational database design.

Star schema is ideal for data warehouse applications because it is designed and tuned to support analysis of business trends and projections. It differs from typical OLTP database design in that it provides a query-centric view of the data. Whereas an OLTP database tends to organize data around specific processes (such as order entry), star
schema answers questions such as “What products are selling well?” “What time of year do products sell best?” and “Which regions have the weakest sales?”

Star schema divides data into two categories: facts and dimensions. Facts are the core data elements being analyzed and dimensions are attributes about the fact. Figure 10 illustrates a dimensional database, where SALES is the fact table and CUSTOMER, PRODUCT, and TIME are the dimension tables.

Star schema’s intuitive method of representing data allows users to easily formulate queries and go directly to the key facts using a set of familiar dimensions. It can also provide significant performance advantages, processing complex, analytical queries in a fraction of the time required by OLTP database systems.

Informix Extended Parallel Server 8.3 also supports 3NF and derivative data structures.

Very Large Data Storage Capacity

The amount of data stored in data warehouse is increasing at a rapid pace. Only a few years ago, data warehouses could be measured in megabytes or a few gigabytes. Today, driven by the increasingly competitive business landscape, users are loading and analyzing an immense amount of historical data into data warehouses to assist with their business decisions. Therefore, it is of the utmost importance that the DBMS managing the data warehouses efficiently handle very large volumes of data.

With a storage capacity in the multiterabyte range, Informix Extended Parallel Server 8.3 is designed to support the largest data warehouses in the world. Furthermore, Informix continues to make enhancements in the configuration parameter of Informix Extended Parallel Server 8.3, ensuring customers that the database server accommodates their continuing storage needs.

Fast Data Access Through Efficient Indexing Methods

For a number of releases, Informix has provided B-tree indexes for fast retrieval of data. B-tree indexes have been very effective in the OLTP arena for retrieving a small number of selected rows (sometimes referred to as low-percentage selectivity). DSS applications, by contrast, tend to retrieve a larger number of rows (or high-percentage selectivity), making random access through a single index more expensive than reading all of the rows in the table in order.

Informix Extended Parallel Server 8.3 offers a host of new indexing methods specifically designed to improve data access for decision support queries. These new DSS indexing methods are fully integrated with the query optimizer; consequently, they can take advantage of parallel query execution and parallel index creation. When created, the indexes improve performance over a wide range of DSS queries, simplify management of DSS systems, and are completely transparent to application users.
The new DSS indexes include:

- multiple index scans, which expand the number of situations where B-tree indexes can be used and improve their performance;
- bitmapped indexes, which provide improved space utilization and much faster AND/OR/NOT/COUNT operations; and
- generalized key (GK) indexes, which allow a more flexible definition of indexing, encompassing joins, virtual columns, and subqueries.

Multiple Index Scan

Multiple index scan is a powerful feature that expands the use of B-tree indexes. It allows a query to use multiple indexes for one table, so that the number of rows scanned for a query is significantly reduced. (See Figure 11.)

Multiple index scans are especially effective for handling complicated, nested, AND-OR-NOT structures that incorporate multiple restrictions. For example, consider the following query:

```sql
select * from CUSTOMER
where (add_date = "12/01/97" or add_date = "12/02/97")
and gender = "F";
```

Using multiple index scans, the database server uses an index on add_date to retrieve the first set of rowids (add_date = “12/01/97” OR add_date = “12/02/97”) and an index on gender to retrieve the other set of rowids (gender = “F”). The results from the two index scans are then merged to determine the rowids that meet both criteria. When the rowids are identified, the rows can be retrieved from the CUSTOMER table. Without the capability to execute this query using
multiple index scans, the database server would have to perform a sequential scan or use only one index.

Multiple-column indexes are sometimes used instead of multiple index scans to achieve the same effect. However, it is important to understand that multiple column indexes work very differently than multiple index scans in that they require all column combinations to be computed ahead of time. This makes multiple-column indexes somewhat restrictive, because not all queries involve the same columns. To resolve this, one would have to create many permutations of multiple column indexes, which would be a tremendous waste of storage space, making them far less useful than multiple index scans.

**Sequential Skip Scan**

Sequential skip scan is different from a normal index scan that retrieves one row at a time. Typically, with a normal index scan, the rowid is read from the index and then used to retrieve the row from the table. This is somewhat inefficient since rowids are not sorted in any physical order, resulting in random access of the pages. Furthermore, if accesses for rows that are close together are not retrieved at the same time, a page can be reread multiple times. This is a tremendous waste of system resources.

Performance of index scans can be drastically improved through the use of sequential skip scans. With a sequential skip scan, rowids are sorted and presented in order. Thus, a scan through the table can pick the next page that has the relevant rows, skipping those pages that do not have the rows. If the page has more than one row, then a single read for the page picks up all rows that are in that page. Overall, sequential skip scan results in significant CPU savings over full table scan, because the number of rows retrieved for expression evaluation is significantly reduced.

For example, consider a table in which rows 1, 256, 5000, 30, 4, and 255 need to be retrieved. Suppose each page in the database holds 10 rows so that the rows just described are stored in the following manner:

Row 1 in the first page;
Row 30 in the third page;
Row 256 in the 25th page;
Row 5000 in the 500th page;
Row 4 in the first page; and
Row 255 also in the 25th page.

Normally, if the index is used to look up the rows, the server would read page 1 to retrieve row 1, page 3 to retrieve row 30, page 25 for row 256, page 500 for row 5000, back to page 1 for row 4, and back to page 25 for row 255.

However, if sequential skip scan is used, the rows that need to be retrieved are first sorted sequentially so that it is presented as rows 1, 4, 30, 255, 256, and 5000. Because rows are sorted in order, data pages are also read in order. This eliminates random I/Os and ensures that a page is read only once. Additionally, sequential skip scan disregards all non-involved data pages, thus skipping over pages 2, 4 through 24, and 26 through 499.
Bitmapped Indexes

Bitmapped indexing has become a popular method for indexing data in the data warehouse arena. The basic idea behind this method of indexing is to use a single bit to indicate that a specific value of a column is associated with a particular row, such that the bit is set to 1 if the entity has the attribute; otherwise the bit is set to 0. The relative position of the bit within the string of bits (or bitmap) is then mapped to the relevant rowid.

A key advantage of using bitmapped indexes is the potential for reduction in storage overhead. For example, instead of using 32 bits to store the rowid of a record with “sports” as the department value, a single bit can be used to indicate whether the department has the value “sports.” If there are 100 million rows in the table, a bitmap indicating which of the rows have \( \text{DEPARTMENT} = \text{“sports”} \) would require 100 million bits, or about 12.5MB, versus a potential of hundreds of megabytes using other methods.

Each attribute value has its own bitmap. For example, if the department attribute has four possible values: “sports”, “automotive”, “garden supplies”, and “electronics,” and a bitmap for \( \text{DEPARTMENT} = \text{“sports”} \), \( \text{DEPARTMENT} = \text{“automotive”} \), \( \text{DEPARTMENT} = \text{“garden supplies”} \), and \( \text{DEPARTMENT} = \text{“electronics”} \). This means that as the possible values for an attribute increase, which is sometimes referred to as high cardinality, the storage space saving starts to diminish. For this reason, bitmapped indexes are best suited for attributes that have fewer values, or low cardinality.

Informix bitmapped indexes use a B-tree implementation to increase efficiency and to reduce storage space. This implementation uses B-tree access to indicate the values of each attribute. The relevant bitmap for the value is then stored at the leaf pages. The bitmap avoids storing rowids as part of the index, thus further reducing storage space. For example, the bitmap for \( \text{DEPARTMENT} = \text{“sports”} \) may look like the following:

\[
(00010000011000101001 \ldots )
\]

The bitmap shows that rows 3, 5, 10, 12, 13, 18, 20, 23, and so forth, have the department value “sports” (skipping over the first 3 bits for rows 0, 1, and 2).

\textbf{Operations AND, OR, NOT, and COUNT}

Another key advantage of bitmapped indexes is the tremendous improvement in CPU speed when performing operations such as \texttt{AND, OR, NOT, and COUNT}. Informix DSS indexes easily perform these operations by using simple programming language algorithms. For example, consider the following algorithm performing an AND operation:

\[
\text{for } (i = 0; i < n; i++) \\
\quad \text{B3}[i] = \text{B1}[i] \& \text{B2}[i];
\]

In this example, B1 is the first index considered and B2 is the second index. The result of the \texttt{AND} operation is then placed in a third index, B3.

Informix DSS indexes use comparable loops to perform \texttt{OR} and \texttt{NOT} operations, and even to \texttt{COUNT} the number of 1 bits in a bitmap that gives the number of rows with a given property.
**Bitmap Compression**

When the number of values for an attribute is large, the bitmap will be sparsely populated and can take up a large amount of storage space. To achieve storage space efficiency where attribute values are large, bitmaps are often compressed. However, when bitmaps are compressed, performing operations such as AND, OR, NOT, and COUNT using the methods described previously becomes less efficient. Thus, an efficient method of bitmap compression must provide a balance between the requirement to achieve storage space savings and support for fast operations of AND, OR, NOT, and COUNT.

After evaluating and testing several methods of compression methods, Informix has selected the most efficient compression method available. This compression method considers various different forms of bitmaps and intelligently switches from one index representation to another. By doing so, Informix can achieve storage-space savings without affecting the efficiency of AND, OR, NOT, and COUNT operations.

**GK Indexes**

To increase performance of queries involving one or more large tables, Informix Extended Parallel Server 8.3 introduces generalized key (GK) indexes. GK indexes—which generalize the use of indexing to allow a broader range of queries—offer a simple yet powerful way of storing the results of a join, expression, or subquery as a key in a B-tree or bitmap index. When created, the optimizer automatically applies the indexes to improve query execution.

Informix Extended Parallel Server 8.3 offers three different GK indexes, including GK join index, GK virtual column index, and GK selective index.

**GK Join Index**

As mentioned earlier, DSS applications frequently require joining of multiple tables. These joins can be performed using several join methods including nested-loop join, sort-merge join, and other join methods that are discussed later in this paper. However, while join algorithms offer the best possible performance for joins that are infrequently used, many complex DSS queries often implement joins using the same columns. To accelerate data access on these joins, Informix introduces GK join index.

A GK join index is essentially a precompiled join. It is an index that consists of references to rows in two or more tables that satisfy the join condition. These references are joined at the index and thus the index might be viewed as a table itself. For example, consider the following:

```sql
create gk index ordersgender on SALES
   (select as key c.gender
    from SALES s, CUSTOMER c
    where s.cid = c.cid)
```

This statement creates a join index for SALES and CUSTOMER on the c.gender column.

Figure 12 shows a join index.
With the GK join index in place, a user can issue the following query “list all sales orders that were purchased by a male customer.” During execution, the optimizer refers to the join index to quickly identify the rows that meet all the conditions. After the rowids are identified (1111, 1114, and 1115), the records can be retrieved from the SALES table. This is achieved without performing any joins among the tables.

To increase efficiency, Informix utilizes bitmaps to represent entries within the GK join index. The bitmap index for the above GK join index would therefore be represented as shown in Figure 13.

GK join indexes are especially useful for dimensional databases. Using GK join indexes, relations between multiple dimension tables can be predefined with the fact table, hence significantly increasing query performance. For example, refer to the dimensional database shown in Figure 10, where SALES is the fact table and CUSTOMER, PRODUCT, and TIME are the dimension tables. With GK join index already created on SALES and CUSTOMER on the c.gender column, as shown in Figure 13. Suppose GK join indexes are created for SALES and PRODUCT on p.package_type column and for SALES and TIME on t.month column:

```
create gk index packagetype on SALES
    (select p.package_type
     from SALES s, PRODUCT p
     where s.pid = p.pid)

create gk index timemonth on SALES
    (select t.month
     from SALES s, TIME t
     where s.day = t.day)
```

Figure 13
Sample bitmapped join index.

<table>
<thead>
<tr>
<th>SALES.rowid</th>
<th>CUSTOMER.gender = M</th>
<th>CUSTOMER.gender = F</th>
</tr>
</thead>
<tbody>
<tr>
<td>1111</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1112</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1113</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1114</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1115</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1116</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1117</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>
The two GK join indexes created as described are shown in Figure 14.

After these indexes are created, the optimizer automatically refers to them when a query involves joining of the referenced tables. For example, consider the following query:

```sql
select sum * 
from SALES s, CUSTOMERS c, PRODUCTS p, 
TIME t
where s.cid = c.cid and s.pid = p.pid 
and s.day = t.day and c.gender = 'M' 
and p.package_type = 'box' and 
t.month = 'Mar';
```

<table>
<thead>
<tr>
<th>SALES.rowid</th>
<th>package_type</th>
<th>package_type</th>
<th>package_type</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>= box</td>
<td>= tube</td>
<td>= envelope</td>
</tr>
<tr>
<td>1111</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1112</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1113</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1114</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1115</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1116</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1117</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>SALES.rowid</th>
<th>month = JAN</th>
<th>month = FEB</th>
<th>month = MAR</th>
</tr>
</thead>
<tbody>
<tr>
<td>1111</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1112</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>1113</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>1114</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1115</td>
<td>1</td>
<td>0</td>
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</tr>
<tr>
<td>1116</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>1117</td>
<td>1</td>
<td>0</td>
<td>0</td>
</tr>
</tbody>
</table>
The described query involves all three dimension tables and the fact table shown in Figure 10. Therefore, the query optimizer can take advantage of all three GK join indexes. First, it identifies all rowids that satisfy \( c\.gender='M' \) using the \text{orderagender} index. Then it identifies all rowids that satisfy \( p\.package\_type='box' \) using the \text{packagetype} index. Finally, it identifies all rowids that satisfy \( t\.month='Mar' \) using the \text{timemonth} index. (See Figure 15.)

When all rowids are identified, the optimizer performs an \text{AND} operation to obtain the rowids that meet all three restrictions. (See Figure 16.)

The resulting rowids are then used to retrieve the rows in the \text{SALES} table. In this example, only one rowid, \#1114, meets all three restrictions. This rowid is used to look up the record in the \text{SALES} table.

\textbf{GK Virtual Column Index}

A GK virtual column index is an index created from the results of an expression involving multiple columns. By creating a GK virtual column index on a commonly used expression, the database server eliminates the requirement to scan the table sequentially and compute the restrictions specified in the query every time it is referenced.

For example, suppose a commonly executed query involves calculating total order cost (merchandise cost, tax, and shipping) with the following query:

\begin{verbatim}
select order\_num from ORDERS
where order\_amt + shipping + tax > 50
\end{verbatim}
The query requires scanning of all rows within the `ORDERS` table, then computing the columns `order_amt`, `shipping`, and `tax`, and comparing the value of the total order amount. By creating a virtual column index that sums the three columns, the optimizer automatically refers to the index to satisfy the query. The virtual index is created as follows:

```
cREATE GK INDEX total_amt ON ORDERS
    (SELECT order_amt + shipping + tax
     FROM ORDERS);
```

Figure 17 illustrates the virtual column index.

```
<table>
<thead>
<tr>
<th>row_ID</th>
<th>total_amt</th>
</tr>
</thead>
<tbody>
<tr>
<td>5011</td>
<td>60</td>
</tr>
<tr>
<td>5012</td>
<td>73</td>
</tr>
<tr>
<td>5013</td>
<td>24</td>
</tr>
<tr>
<td>5014</td>
<td>18</td>
</tr>
<tr>
<td>5015</td>
<td>55</td>
</tr>
<tr>
<td>5016</td>
<td>36</td>
</tr>
<tr>
<td>5017</td>
<td>22</td>
</tr>
</tbody>
</table>
```

**Figure 17**
Sample virtual column index.

With the virtual column index `total_amt` in place, the optimizer automatically identifies the rowids with values greater than 50 (rowids 5011, 5012, and 5015) so the records can be retrieved from the order table.

**GK Selective Index**

A selective index is an index created from a subquery that selects a subset of the total rows. Two key benefits of selective index are:

1) it speeds up the actual index build since it only builds on a subset of the total rows, and

2) it speeds up query time by only indexing values that users would be likely to search on. Unlike a conventional index that has an entry for every row, a selective index can save potentially large amount of storage space since only frequently accessed rows are indexed.

For example, suppose the following index was created:

```
cREATE GK INDEX current ON SALES
    (SELECT department FROM SALES
     WHERE day >= 1/1/96);
```

With this index in place, the optimizer automatically uses the index when appropriate. For example, the index can be used in the following query:

```
SELECT sum(dollar_sales)
FROM SALES
WHERE day = 9/1/96
```

**Enhanced Join Methods**

Decision support queries often require the joining of multiple tables on arbitrary columns. These columns are often without indexes. Joining these non-index columns can be very expensive and time consuming. To address this situation, many database vendors offer sort-merge joins where the tables involved in the join are scanned and sorted based on the join column. After the rows are sorted, the results can be merged sequentially.
Informix offers two additional join methods to improve the efficiency of joining within DSS queries. They are hash join and star-query optimization.

**Hash Join**
Hash joins are used when one of the two join tables does not have an index on the join column, or when the database server must read a large number of rows from both tables. This join method is more efficient than the sort-merge join because no sorting is required.

With hash joins, one table, generally the smaller table (also known as *build input*), is first scanned and used to create a hash table based on the conditional expressions within the WHERE clause (also known as filter). (See Figure 18.) The hash table can consist of a series of tables, each having an address derived from the key value by applying a hash function. After the first table has been scanned and placed in the hash table, the second table is read sequentially, and each row is looked up in the hash table to see if a join can be made. The process of looking up the hash table by the second table is also known as the *probe phase*. (See Figure 19.)

Often, because the optimizer chooses the smallest table as the build table, the entire build input is small enough to be placed in memory to significantly increase the performance of the join. If the build input does not fit into memory, it is partitioned by the hash join build phase, so that a subset of the table is in memory. Other partitions are written to disk. When the larger probe table is read, it is either matched with the hash table stored in memory or written out into a separate partition file. This process results in the creation of several probe partitions to match with the build partitions. When the probe phase is completed with the first partition, the next set of build and probe partitions can be processed independently in pairs.
For example, consider the following query:

```sql
select sum(sales.amount)
from SALES s, CUSTOMER c
where s.cid = c.id
and c.state = “CA”
```

Suppose a hash join was used in the query just described. During the build phase, the `CUSTOMER` table is read and a hash table is created for all IDs that match the join condition of `c.state = “CA”`. During the probe phase, the `SALES` table is read once, and each row is matched with IDs in the hash table. The resulting rows are then summed to produce the query results.

Hash joins are often more efficient than a sort-merge join because no sorting is required. By contrast, a sort-merge join would require both tables to be sorted; therefore it becomes less efficient whenever the join requires large tables.

**Star Query Optimization**

Star query optimization is a patented algorithm designed to reduce join processing of queries joining multiple, smaller dimension tables with a very large fact table. This new join method increases join efficiency by combining new indexing technologies (bitmapped filters, multiple index scans, and sequential skip scan) with the hash join algorithm. When used successfully, this technique results in a tremendous reduction in the number of rows read during the hash join probe phase. The result is a performance gain of up to 100 times greater with other join methods.

The basic query plan for star query optimization involves scanning and applying the filters to the dimension tables. The resulting rows are used to build a hash table. While the hash table is being built, the dimension table primary keys are “pushed down” to the fact table. The fact table can use these “push keys” to perform an efficient index scan or to construct a bitmap filter. In either case, rows from the fact table are eliminated from the probe phase of the hash joins. The remaining fact table rows are then used for join processing with all the dimension tables in a pipeline fashion to complete the query.

For example, consider the following query using the star schema illustrated in Figure 10:

```sql
select c.name, p.name, sum(s.amount)
from SALES s, CUSTOMER c, PRODUCT p, DATE d
where s.cid = c.cid and
  s.pid = p.pid and
  p.category = “software” and
  s.did = d.did and
  d.year = “1998”
group by c.name, p.name;
```
The query just described should return the total sales of each software product by customer for 1998. A typical pushdown plan for this query is shown in Figure 20.

In this example, the filters d.year = “1998” and p.category = “software” are applied to the DATE and PRODUCT tables. The resulting rows are used to build the corresponding DATE and PRODUCT hash tables as well as “push down” to the sales table to reduce the number of rows for join processing.

To understand the performance implications of the star query optimization, assume that the SALES table has 1 million rows. Also assume that the filters on each of the dimension tables provide 1/10 selectivity and that this selectivity transfers uniformly to the sales table. Thus, the resulting table scan from applying the “push keys” only produce 10,000 rows for join processing. This number is substantially less than the one million rows that would otherwise needed to be processed in a non-optimized plan. (See Figure 21.)
As mentioned earlier, two methods are offered to push the filter down to the fact table. They are referred to as index pushdown and bit vector pushdown.

**Index Pushdown**
Index pushdown is implemented by sorting the primary key of the dimension table and sending the sorted keys to the fact table scan. The sorted keys are used to perform index lookups on the fact table, resulting in a list of sorted rowids which is then used to perform a sequential skip scan of the sales table.

**Bit Vector Pushdown**
With bit vector pushdown, the dimension table primary key is hashed and used to set a bit in a bitmap. When the fact table is scanned, each row is tested against the bitmap by hashing on the corresponding foreign key and checking whether the appropriate bit is set in the bitmap. If the bit is on, the row is kept for join processing; otherwise it is discarded.

Star query optimization is completely integrated with the database server. Thus, it is invoked automatically by the optimizer, which means no special coding or “hints” are necessary. This optimization technique also eliminates the need for a special-purpose query engine.

**Enhanced SQL Extensions**
Unlike OLTP operations that are process-oriented, decision support operations tend to be very query-centric, thus are often used to analyze business trends and product profitability. Understanding that decision support queries often ask same types of questions, Informix Extended Parallel Server 8.3 offers a variety of SQL extensions to speed up the execution of certain types of DSS queries.

For example, many DSS queries require the retrieval of first, last, top, or bottom N records such as the top 10 selling products, the worst 5 performing regions, the first 100 customer matching a profile, and so forth. To address these DSS queries, Informix provides a new SQL extension called *First N*. First N lets users specify the number of records returned from a query. This can drastically reduce the number of rows shipped to the clients. For instance, instead of potentially shipping hundreds of rows, only the top 10 rows are shipped. Additionally, it can accelerate the sort process, since the sort process only needs to process a fraction of the records.
Another new extension, Sampling, lets users get an approximate idea of what is contained in a table without having to scan the entire table. By using Sampling, the user can obtain important information about a table, such as sales trends, much faster than executing a query that scans the entire table. For example, sampling 1,000 records from a 10 million row table is significantly faster than reading all the rows.

Informix Extended Parallel Server 8.3 also extended the CASE statement to allow incorporation of conditional expression within columns as part of an SQL statement. By using this new SQL extension, users can significantly reduce the complexity of database operations.

For example, the following example shows a CASE statement with multiple expressions:

```sql
select case
  when sales.amount < 100 then "small sales"
  when sales.amount < 1000 then "mid-range sales"
  else "large sales"
end
from SALES
sum (sales.amount)
group by 1
```

Through these new SQL extensions, Informix significantly increases the speed of execution for commonly executed decision support queries. Consequently, critical information is delivered faster to business managers, enabling them make key decisions about their companies’ products and services in a more timely manner.
Informix Extended Parallel Server 8.3 incorporates several new features to improve the management of large data warehouses. They include a powerful parallel data loader, an improved algorithm for altering tables, and tools for enhancing query management.

Query Management
Considering the ad hoc nature of this environment—an environment in which the type, quantity, and complexity of queries being submitted is unpredictable—data warehouse administrators must be equipped with query management tools to assist with controlling the impact of intensive, concurrent query processing.

Informix Extended Parallel Server 8.3 offers a unique feature called memory grant manager, which lets administrators and programmers control certain aspects of query execution, such as degree of parallelism, query execution ordering, and so forth. Informix Extended Parallel Server 8.3 also provides several features to offer users more autonomy and control over the execution ordering of their queries. These features include scheduling levels, PDQpriority ranges, and two admission policies.

Scheduling Levels
Scheduling levels provide a mechanism for ranking query importance by assigning a value from 1 through 100 to a query. It denotes the importance that a user places on a query, which the database server uses for guidance when deciding the next query to admit.

PDQpriority Ranges
PDQpriority ranges provide a mechanism to set an acceptable range of memory for a query, where the largest PDQpriority value in the range is the desired resource allocation, and the smallest PDQpriority value is the minimum acceptable memory allocation for the query. For example, a query with a PDQpriority of 20 to 30 can be started when 25 percent of memory is available. If it had a value of 30, it would have to wait until the full 30 percent of resources were available.

PDQpriority range contributes to improved memory utilization by allowing the database server to better exploit available memory. By allowing users to specify an acceptable range for memory allocation, Informix avoids situations where a query is blocked when almost enough memory is available. It also avoids situations where users may set memory allocations artificially low to ensure the query is executed.

Admission Policy
Two policies are available to determine how scheduling levels and PDQpriority ranges are used to choose the actual query execution order. In “strict ordering” the highest level queries are run first and within each level, admission is on a first come, first served basis. This policy could delay a less important query indefinitely (also known as starvation).
The second policy is “fair ordering” (no starvation) in which queries are aged based on scheduling level, PDQpriority, and wait time. This causes lower level queries that have been waiting a long time to be executed ahead of higher level queries with very little wait time. For queries with equal importance (same scheduling level), a query with the lowest PDQpriority tend to be chosen in favor of queries with higher PDQpriority.

The fair ordering admission policy favors lower PDQpriority queries based on the assumption that low PDQpriority queries are smaller and less complex than high PDQpriority queries. Reducing the wait time of small, fast queries can result in improvement in query response time as well as an increase in system throughput. The additional wait time for large queries does not significantly increase response time since it is insignificant compared to the execution time.

**Parallel Loader**

With the advent of decision-support applications, companies today are loading and unloading large amounts of data from operational databases into large data warehouses on a regular basis, sometimes as often as daily. If the data loaded is incremental, then the speed of the load is not a great concern. However, in many cases, the data loaded is a refresh of the entire database and the performance of the database loader becomes critical.

The Informix high-performance parallel loader utility addresses data loading and unloading performance by using all the system resources available, thereby allowing the data to be loaded and unloaded in parallel, to and from Informix databases.

The parallel loader utility can load and unload data very quickly through its ability to read data from multiple sources and load data across multiple disks in parallel. This is achieved through I/O parallelism to and from media devices, which can significantly increase the speed of the load over serial load. This utility is especially important when loading large databases, enabling customers to load multiple gigabytes of data per hour.

The Informix high-performance loader also supports the following key features:

- Data can be loaded or unloaded at the table-partition level.
- Data can be loaded from or unloaded to files, tapes, or application pipes.
- A conversion utility supports non-Informix sources such as binary, EBCDIC, ASCII, and so forth.
- A GUI interface enhances ease of use.

With the high-performance loader, customers have the option to disable referential checking, logging, triggers, and drop indexes to substantially increase the speed of the loading. Or, if load speed is not a concern, customers can choose to enforce all database constraints as the data is added.
**Alter Fragment**

After a table and its associated indexes have been partitioned, they can be altered using the `alter fragment` command. One reason for modifying how tables and indexes are partitioned is to combine tables that contain identical table structures into a single fragmented table (also known as attached table) or detaching a table fragment from a fragmentation strategy and place it in a new table (also known as detached table). Attached and detached tables are used often in situations where limited disk space necessitates moving outdated data from disks onto other forms of storage media.

A common scenario in which this feature is useful is when a customer maintains a rolling window of data. For example, a customer can have one table that contains 12 months worth of data, each month within its own fragment. A second table contains only the current month’s data. At the end of each month, customers attach the table containing the current months data as a new fragment to the 12 month table. The oldest month’s data has its fragment detached. This functionality provides customers with a very clean, very fast import of data with minimal impact on the base table.

To illustrate, let’s assume that the oldest month in this case is June 1996 and orders for this month are stored in dbspace db0696. The following shows the `alter fragment` command to detach dbspace db0696 from the ORDER table and place it into the old_ORDER table.

```
alter fragment on table ORDER
detach
db0696 old_ORDER
```

When created, old_ORDER can be copied onto another form of storage and deleted from disk.

To store orders received for the current month, a new table, new_ORDER, is created. Because ORDER and new_ORDER use the same table structure, the alter fragment command can be used to attach the two tables into a single fragmented table. The command for attaching new_ORDER to ORDER table is shown below:

```
alter fragment on table ORDER
attach
new_ORDER
```
Conclusion

Informix Extended Parallel Server 8.3 is designed to respond to the increasing demand of decision support applications. Informix Extended Parallel Server 8.3 incorporates a set of robust data warehousing features to enable fast data access, analysis, and management. Regardless of the processing environment and the type of parallel hardware architecture, Informix Extended Parallel Server 8.3 delivers the performance and scalability organizations need to effectively handle complex, large-scale decision support operations.
About Informix

Informix Corporation, based in Menlo Park, California, provides innovative database solutions that assist the world's major corporations attain competitive advantage. Informix is widely recognized as the technology leader for corporate computing environments ranging from small workgroups to very large parallel processing applications. Informix's database server, application development tools, superior customer service, and strong partnerships enable the company to be at the forefront of major information technology solution areas including data warehousing, high performance OLTP, and Web/e-commerce.

For more information, contact the sales office nearest you or visit our Web site at www.informix.com.
### INFORMIX REGIONAL SALES OFFICES

<table>
<thead>
<tr>
<th>Region</th>
<th>Phone</th>
</tr>
</thead>
<tbody>
<tr>
<td>Asia Pacific</td>
<td>65 298 1716</td>
</tr>
<tr>
<td>Canada (Toronto)</td>
<td>416 730 9009</td>
</tr>
<tr>
<td>Europe/Middle East/Africa</td>
<td>44 181 818 1000</td>
</tr>
<tr>
<td>Federal</td>
<td>703 847 2900</td>
</tr>
<tr>
<td>Japan</td>
<td>81 3 5562 4500</td>
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<td>Latin America</td>
<td>305 931 9592</td>
</tr>
<tr>
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<td>North America</td>
<td>800 331 1763</td>
</tr>
<tr>
<td>Federal</td>
<td>650 926 6300</td>
</tr>
</tbody>
</table>

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